GROUP TECHNOLOGY AND FLEXIBLE MANUFACTURING SYSTEMS

Group Technology

Flexible Manufacturing Systems and Cells

Overview of Group Technology (GT)

- Parts in the medium production quantity range are usually made in batches
- Disadvantages of batch production:
  - Downtime for changeovers
  - High inventory carrying costs
- GT minimizes these disadvantages by recognizing that although the parts are different, there are groups of parts that possess similarities
- GT exploits the part similarities by utilizing similar processes and tooling to produce them
- GT can be implemented by manual or automated techniques
- When automated, the term *flexible manufacturing system* is often applied

Group Technology Defined

- An approach to manufacturing in which similar parts are identified and grouped together in order to take advantage of their similarities in design and production
- Similarities among parts permit them to be classified into part families
- In each part family, processing steps are similar
- The improvement is typically achieved by organizing the production facilities into manufacturing cells that specialize in production of certain part families

Part Family

- A group of parts that possess similarities in geometric shape and size, or in the processing steps used in their manufacture
- Part families are a central feature of group technology
- There are always differences among parts in a family
- But the similarities are close enough that the parts can be grouped into the same family

Two parts that are identical in shape and size but quite different in manufacturing:

(a) 1,000,000 units/yr, tolerance = ±0.010 inch, 1015 CR steel, nickel plate
(b) 100/yr, tolerance = ±0.001 inch, 18-8 stainless steel
Ten parts that are different in size and shape, but quite similar in terms of manufacturing
All parts are machined from cylindrical stock by turning; some parts require drilling and/or milling

Ways to Identify Part Families
1. **Visual inspection** - using best judgment to group parts into appropriate families, based on the parts or photos of the parts
2. **Production flow analysis** - using information contained on route sheets to classify parts
3. **Parts classification and coding** - identifying similarities and differences among parts and relating them by means of a coding scheme

Parts Classification and Coding

Most classification and coding systems are one of the following:
- Systems based on part design attributes
- Systems based on part manufacturing attributes
- Systems based on both design and manufacturing attributes

Part Design Attributes
- Major dimensions
- Basic external shape
- Basic internal shape
- Length/diameter ratio
- Material type
- Part function
- Tolerances
- Surface finish

Part Manufacturing Attributes
- Major process
- Operation sequence
- Batch size
- Annual production
- Machine tools
- Cutting tools
- Material type
Three structures used in classification and coding schemes

- Hierarchical structure, known as a mono-code, in which the interpretation of each successive symbol depends on the value of the preceding symbols.
- Chain-type structure, known as a polycodes, in which the interpretation of each symbol in the sequence is always the same; it does not depend on the value of preceding symbols.
- Mixed-mode structure, which is a hybrid of the two previous codes.

Some of the important systems

- Opitz classification system – the University of Aachen in Germany, nonproprietary, Chain type.
- Brisch System – (Brisch-Birn Inc.)
- CODE (Manufacturing Data System, Inc.)
- CUTPLAN (Metcut Associates)
- DCLASS (Brigham Young University)
- MultiClass (OIR: Organization for Industrial Research), hierarchical or decision-tree coding structure.
- Part Analog System (Lovelace, Lawrence & Co., Inc.)

Basic Structure of the Opitz Parts Classification and Coding System

<table>
<thead>
<tr>
<th>Digit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Part shape class: rotation versus nonrotational (Figure 22.1). Rotational parts are classified by length-to-diameter ratio. Nonrotational parts by length, width, and thickness.</td>
</tr>
<tr>
<td>2</td>
<td>External shape features; various types are distinguished.</td>
</tr>
<tr>
<td>3</td>
<td>Rotational machining. This digit applies to internal shape features (e.g., holes, threads) on rotational parts, and general rotational shape features for nonrotational parts.</td>
</tr>
<tr>
<td>4</td>
<td>Plane machined surfaces (e.g., flats, slots).</td>
</tr>
<tr>
<td>5</td>
<td>Auxiliary holes, gear teeth, and other features.</td>
</tr>
<tr>
<td>6</td>
<td>Dimensions—overall size.</td>
</tr>
<tr>
<td>7</td>
<td>Work material (e.g., steel, cast iron, aluminum).</td>
</tr>
<tr>
<td>8</td>
<td>Original shape of raw material.</td>
</tr>
<tr>
<td>9</td>
<td>Accuracy requirements.</td>
</tr>
</tbody>
</table>

Basic structure of the Opitz system of parts classification and coding
### Form code (digits 1-5) for rotational parts in the Opitz coding system

<table>
<thead>
<tr>
<th>Digit 1</th>
<th>Digit 2</th>
<th>Digit 3</th>
<th>Digit 4</th>
<th>Digit 5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Part class</td>
<td>External shape, internal shape elements</td>
<td>Internal shape, internal shape elements</td>
<td>Plane surface machining</td>
<td>Auxiliary holes and gear teeth</td>
</tr>
<tr>
<td>0</td>
<td>L/D ≤ 0.5</td>
<td>Smooth, no shape elements</td>
<td>No hole, no breakthrough</td>
<td>No auxiliary hole</td>
</tr>
<tr>
<td>1</td>
<td>0.5 &lt; L/D &lt; 3</td>
<td>No shape elements</td>
<td>No shape elements</td>
<td>Axial, not on pitch circle diameter</td>
</tr>
<tr>
<td>2</td>
<td>L/D ≥ 3</td>
<td>Thread</td>
<td>No shape elements</td>
<td>Axial on pitch circle diameter</td>
</tr>
<tr>
<td>3</td>
<td>Functional groove</td>
<td>Smooth or stepped to one end</td>
<td>Thread</td>
<td>Radial, not on pitch circle diameter</td>
</tr>
<tr>
<td>4</td>
<td>No shape elements</td>
<td>Stepped to both ends</td>
<td>Functional groove</td>
<td>No gear teeth</td>
</tr>
<tr>
<td>5</td>
<td>Thread</td>
<td>Stepped to both ends</td>
<td>No shape elements</td>
<td>Axial and/or radial and/or other direction</td>
</tr>
<tr>
<td>6</td>
<td>Functional groove</td>
<td>Functional groove</td>
<td>External external</td>
<td>External plane surface and/or slot, external spline</td>
</tr>
<tr>
<td>7</td>
<td>Functional cone</td>
<td>Functional cone</td>
<td>No shape elements</td>
<td>Axial and/or radial on PCD and/or other directions</td>
</tr>
<tr>
<td>8</td>
<td>Operating thread</td>
<td>Operating thread</td>
<td>External plane surface and/or slot</td>
<td>Spur gear teeth</td>
</tr>
<tr>
<td>9</td>
<td>All others</td>
<td>All others</td>
<td>Internal plane surface and/or slot</td>
<td>Bevel gear teeth</td>
</tr>
<tr>
<td>9</td>
<td>All others</td>
<td>All others</td>
<td>Internal and external</td>
<td>Other gear teeth</td>
</tr>
<tr>
<td>9</td>
<td>All others</td>
<td>All others</td>
<td>Polygons, groove and/or slot</td>
<td>All others</td>
</tr>
</tbody>
</table>

### Example 1: A part coded 20801
- 2 - Parts has L/D ratio >= 3
- 0 - No shape element (external shape elements)
- 8 - Operating thread
- 0 - No surface machining
- 1 - Part is axial

### Example 2: given the part design shown define the "form code" using the Opitz system

![Part Design](image)

Step 1: The total length of the part is 1.75, overall diameter 1.25,  
L/D = 1.4 (code 1)
Step 2: External shape - a rotational part that is stepped on both with one thread (code 5)
Step 3: Internal shape - a through hole (code 1)
Step 4: By examining the drawing of the part (code 0)
Step 5: No auxiliary holes and gear teeth (code 0)

**Code: 15100**

Square cast-iron flange classified by the Opitz system.

**MultiClass – developed by the Organization for Industrial Research (OIR)**

- First 18 digits of the Multiclass Classification and Coding System

<table>
<thead>
<tr>
<th>Digit</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Code system prefix</td>
</tr>
<tr>
<td>1</td>
<td>Main shape category</td>
</tr>
<tr>
<td>2, 3</td>
<td>External and internal configuration</td>
</tr>
<tr>
<td>4</td>
<td>Machined secondary elements</td>
</tr>
<tr>
<td>5, 6</td>
<td>Functional descriptors</td>
</tr>
<tr>
<td>7–12</td>
<td>Dimensional data (length, diameter, etc.)</td>
</tr>
<tr>
<td>13</td>
<td>Tolerances</td>
</tr>
<tr>
<td>14, 15</td>
<td>Material chemistry</td>
</tr>
<tr>
<td>16</td>
<td>Raw material shape</td>
</tr>
<tr>
<td>17</td>
<td>Production quantity</td>
</tr>
<tr>
<td>18</td>
<td>Machined element orientation</td>
</tr>
</tbody>
</table>

MultiClass Coding System example – the rotational part design
MultiClass code number for the rotational part

Possible ambiguity with a coding system

Benefits of a Well-Designed Classification and Coding System
- Facilitates formation of part families
- Permits quick retrieval of part design drawings
- Reduces design duplication
- Promotes design standardization
- Improves cost estimating and cost accounting
- Facilitates NC part programming by allowing new parts to use the same part program as existing parts in the same family
- Computer-aided process planning (CAPP) becomes feasible

**Composite Part Concept**

- A composite part for a given family is a hypothetical part that includes all of the design and manufacturing attributes of the family
- In general, an individual part in the family will have some of the features of the family, but not all of them
- A production cell for the part family would consist of those machines required to make the composite part
- Such a cell would be able to produce any family member, by omitting operations corresponding to features not possessed by that part

![Composite Part Concept Diagram](image1)

- Composite part concept: (a) the composite part for a family of machined rotational parts, and (b) the individual features of the composite part

**Composite Part Features and Corresponding Manufacturing Operations**

<table>
<thead>
<tr>
<th>Design feature</th>
<th>Corresponding operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. External cylinder</td>
<td>Turning</td>
</tr>
<tr>
<td>2. Face of cylinder</td>
<td>Facing</td>
</tr>
<tr>
<td>3. Cylindrical step</td>
<td>Turning</td>
</tr>
<tr>
<td>4. Smooth surface</td>
<td>External cylindrical grinding</td>
</tr>
<tr>
<td>5. Axial hole</td>
<td>Drilling</td>
</tr>
<tr>
<td>6. Counterbore</td>
<td>Counterboring</td>
</tr>
<tr>
<td>7. Internal threads</td>
<td>Tapping</td>
</tr>
</tbody>
</table>

**Machine Cell Designs (Types of GT cells):**

(a) Single machine
(b) Multiple machines with manual handling
(c) Multiple machines with mechanized handling
(d) Flexible manufacturing cell
(e) Flexible manufacturing system
Benefits of Group Technology
- Standardization of tooling, fixtures, and setups is encouraged
- Material handling is reduced
  - Parts are moved within a machine cell rather than entire factory
- Process planning and production scheduling are simplified
- Work-in-process and manufacturing lead time are reduced
- Improved worker satisfaction in a GT cell
- Higher quality work

Problems in Group Technology
- Identifying the part families (the biggest problem)
  - If the plant makes 10,000 different parts, reviewing all of the part drawings and grouping the parts into families is a substantial task
- Rearranging production machines in the plant into the appropriate machine cells
  - It takes time to plan and accomplish this rearrangement, and the machines are not producing during the changeover

Flexible Manufacturing System
- A highly automated GT machine cell, consisting of a group of processing stations (usually CNC machine tools), interconnected by an automated material handling and storage system, and controlled by an integrated computer system
- The FMS relies on the principles of GT
  - No manufacturing system can produce an unlimited range of products
  - An FMS is capable of producing a single part family or a limited range of part families

Flexibility Tests in an Automated Manufacturing System
- Automated manufacturing cell with two machine tools and robot. Is it a flexible cell?

To qualify as being flexible, a manufacturing system should satisfy the following criteria (“yes” answer for each question):
1. Can it process different part styles in a non-batch mode?
2. Can it accept changes in production schedule?
3. Can it respond gracefully to equipment malfunctions and breakdowns?
4. Can it accommodate introduction of new part designs?
If the automated system does not meet these four tests, it should not be classified as a flexible manufacturing or cell.

Is the Robotic Work Cell Flexible?

1. Can it machine different part configurations in a mix rather than in batches?
2. Can production schedule and part mix be changed?
3. Can it operate if one machine breaks down?
   - Example: while repairs are being made on the broken machine, can its work be temporarily reassigned to the other machine?
4. As new part designs are developed, can NC part programs be written off-line and then downloaded to the system for execution?

This fourth capability also requires that the tooling in the CNC machines as well as the end effector of the robot are suited to the new part design.

FMS Components

- Hardware components
  - Workstations - CNC machines in a machining type system
  - Material handling system - means by which parts are moved between stations
  - Central control computer - to coordinate the activities of the components so as to achieve a smooth overall operation of the system
- Software and control functions
- Human labor

Five Types of FMS Layouts

1. In-line
2. Loop
3. Ladder
4. Open field
5. Robot-centered cell

The basic layout of the FMS is established by the material handling system

Three of the five FMS layout types: (a) in-line

Key: Aut = automated station; L/UL = load/unload station; Insp = inspection station; AGV = automated guided vehicle; AGVS = automated guided vehicle system

(b) Ladder layout
Typical Computer Functions in a FMS

- **NC part programming** - development of NC programs for new parts introduced into the system
- **Production control** - product mix, machine scheduling, and other planning functions
- **NC program download** - part program commands must be downloaded to individual stations
- **Machine control** - individual workstations require controls, usually CNC

More Computer Functions in a FMS

- **Workpart control** - monitor status of each workpart in the system, status of pallet fixtures, orders on loading/unloading pallet fixtures
- **Tool management** - tool inventory control, tool status relative to expected tool life, tool changing and resharpening, and transport to and from tool grinding
- **Transport control** - scheduling and control of work handling system
- **System management** - compiles management reports on performance (utilization, piece counts, production rates, etc.)

Duties Performed by Human Labor

- Loading and unloading parts from the system
- Changing and setting cutting tools
- Maintenance and repair of equipment
- NC part programming
- Programming and operating the computer system
- Overall management of the system
FMS Applications
- Machining – most common application of FMS technology
- Assembly
- Inspection
- Sheet metal processing (punching, shearing, bending, and forming)
- Forging

Application characteristics of flexible manufacturing systems and cells relative to other types of production systems

Typical FMS Benefits
- Higher machine utilization than a conventional machine shop due to better work handling, off-line setups, and improved scheduling
- Reduced work-in-process due to continuous production rather than batch production
- Lower manufacturing lead times
- Greater flexibility in production scheduling